OMRON

Autonomous Mobile Robots HD Series

Autonomous Mobile Robots that self-navigate to transport payloads up to 1500 Kg

- Natural feature navigation: Automatically plans efficient routes and prevents collisions
- Fleet management: Operates in coordination with a fleet of up to 100 AMRs
- Easy deployment: Installs quickly, without facility modifications



Ordering Information

Туре	HAPS	Side Lasers	Charging Station	Pendant	Top Plate	Part Number
	No	No	- No	No	No	37480-00000
		Yes				37480-00010
		No	Yes	Yes	Yes	37480-10004
	Single	No	No	No	No	37480-00100
		Yes				37480-00110
HD-1500		No	Yes	Yes	Yes	37480-10104
		Yes				37480-10114
	Double	No	No	No	No	37480-00200
		Yes				37480-00210
		No	Yes	Yes	Yes	37480-10204
		Yes				37480-10214

Note: 1. To ensure proper fleet management, please contact an OMRON representative before ordering AMRs to add to an existing fleet.
2. The battery for the HD-1500 must be ordered separately (part number 68330-000).

Accessories and Optional Items

Item	Details	Part Number
EM2100	Network appliance that acts as a Fleet Manager or Fleet Simulator	14328-200
Top Plate Kit	Upper plate kit of the AMR. It is not necessary for building a customer payload structure	68950-000
Pendant	Handheld, external input device for manually driving an AMR. It is typically used for map creation	68940-000L
Charging Station	Includes a Power Supply Box and Docking Target	68910-010
Power Supply Box	Supplies power to the Docking Target or battery for charging purposes	68310-000
Docking Target	A fixed object that the AMR docks to for autonomous charging. Connects to the Power Supply Box	68910-000
Battery	Removable and rechargeable power source for the AMR	
Side Laser Extension Cables,	1 m length	22115-000F
Communication	2 m length	22117-000F
Side Laser Extension Cables,	1 m length	22800-000F
Power	2 m length	22802-000F
Wireless Antenna Extension Kit	Two cables, 2 m each, two dipole antennas	68955-000
CAPS License Licensed version of the Cell Alignment Positioning System		20271-805

HD Series

Fleet Operations Workspace Solutions

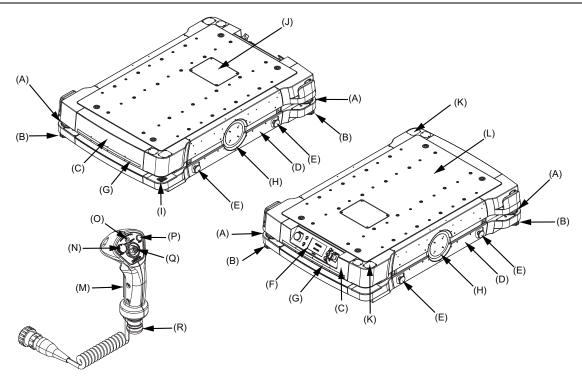
Product Name	Configuration	Part Number
Primary Fleet Operations Workspace (FLOW) Core License, 1 Year *1	Entitlement for a 1 year renewable Primary FLOW Core license, runtime and development, per AMR connection	20271-800
Primary Fleet Operations Workspace (FLOW) Core License, 5 Year *2	Entitlement for a 5 year renewable Primary FLOW Core license, runtime and development, per AMR connection	20271-806
Secondary Fleet Operations Workspace (FLOW) Core License, 1 Year *1	Entitlement for a 1 year renewable Secondary FLOW Core license per fleet, redundant runtime	20271-802
Secondary Fleet Operations Workspace (FLOW) Core License, 5 Year *2	Entitlement for a 5 year renewable Secondary FLOW Core license per fleet, redundant runtime	20271-807
Primary Fleet Manager	EM2100 Appliance with Temporary 120 Day Fleet Operations Workspace License	20271-900
Secondary Fleet Manager	EM2100 Appliance with Temporary 120 Day Fleet Operations Workspace License	20271-901
Bundle. Fleet Simulator	EM2100 appliance with Entitlement for perpetual Fleet Simulator License	20271-903
License, Fleet Simulator	Entitlement for perpetual Fleet Simulator license for use with existing EM2100 appliance, simulation runtime and development	20271-804
Lipping Elect Operations Workspace iQ	Entitlement for a 1 year renewable FLOW iQ license	20271-701
License, Fleet Operations Workspace iQ	Entitlement for a 5 year renewable FLOW iQ license	20271-705

Note: To obtain the latest version of the Fleet Operations Workspace (FLOW) Core software, contact your local OMRON representative. Please note that an active subscription is required for access to software upgrades.

*1. Expiration of a 1 year subscription license without renewal will result in cessation of the fleet management functions of the OMRON AMR solution until the license is renewed.

*2. After four consecutive 1 year renewals (for a total of 5 years) or after purchase of a 5 year license, all fleet management functions will continue to operate without requiring subsequent subscription renewals. Please note that an active subscription will still be required to have access to subsequent software releases, including bug fixes, feature upgrades and performance improvements.

Features and Components



ltem	Description	Item	Description
А	Safety Laser Scanner	J	User Access Panel
В	Low Laser	К	Wireless Antennas
С	Front / Rear Skin	L	Payload Mounting Surface (Top Plate shown)
D	Side Skin	М	Three-position Enabling Switch
Е	E-STOP Button *1	Ν	Speed Control
F	Operator Panel	0	Power Indicator LED
G	Light Strip	Р	Goal Button
Н	Light Disc	Q	Directional Control Stick
Ι	Charging Contacts	R	E-STOP Button

***1.** Additional E-STOP buttons are provided on the Operator Panel and the Pendant.

Specifications

HD-1500

Environment Arr Arr Or Alt Ing Floor Conditions	y) mbient temperature torage temperature mbient humidity perating environment lititude gress Protection Class loor requirements linimum floor flatness raversable step raversable gap limb grade	506.5 kg 5 to 40°C -20 to 60°C 5 to 95% (non-condensing) Indoor usage only, no excessive dust, no corrosive gas 2000 m maximum IP20 No water, no oil, no dirt Fr25 (ACI 117 standard) 10 mm max. 20 mm max.
Environment Arr Arr Or Alt Ing Floor Conditions	torage temperature mbient humidity perating environment lititude ogress Protection Class loor requirements linimum floor flatness raversable step raversable gap	-20 to 60°C 5 to 95% (non-condensing) Indoor usage only, no excessive dust, no corrosive gas 2000 m maximum IP20 No water, no oil, no dirt F=25 (ACI 117 standard) 10 mm max.
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Floor Tra Conditions	linimum floor flatness raversable step raversable gap	FF25 (ACI 117 standard) 10 mm max.
Floor Conditions	raversable step raversable gap	10 mm max.
Conditions	raversable gap	
In		20 mm max.
	limb grade	
Cli		Max. 3° incline (5° with FLOW 3.0 or later)
Ro Navigation	outing	Autonomous routing by localizing with safety scanning laser, based on environment mapping
-	nvironmental map-making method	Scan by driving the AMR through the environment, and upload the scan data to the MobilePlanner
Payload Rating		1500 kg
Ru	un Time *1	12.5 h (no payload), 9 h (full payload)
Ma	laximum speed	1800 mm/s
Ma	aximum rotation speed	60 °/s
Sv	wing radius	982 mm
Tu	urn radius	0 mm
Ma	aximum translational acceleration	900 mm/s ²
Ma	laximum rotational cceleration/deceleration	150 °/s ²
Mobility	laximum moment of inertia	490 kg-ms ²
line in the second seco		To a position: ±50 mm
		To standard target: ± 25 mm, $\pm 2^{\circ}$
Ste	top position repeatability (single AMR)	With CAPS: ±8 mm, ±0.5°
		With HAPS: ±8 mm, ±0.4°
		To a position: ±70 mm
Ste	top position repeatability (Fleet)	To standard target: ±35 mm, ±2°
		With CAPS: ±16 mm, ±0.5° With HAPS: ±10 mm, ±0.75°
Drive wheels Ma	laterials	Non-marking, static dissipative polyurethane on steel rim
	laterials	Non-marking polyurethane on cast iron rim.
		48 to 56 VDC
Auxiliary Power	nregulated	
	egulated	23.0 to 25.2 VDC
	armonized standard	EN ISO 12100, EN ISO 13849-1, EN 60204-1
	elevant standard	ISO 10218, UL1564, UL2271, UL1740
	/ireless	IEEE 802.11 a/b/g/n/ac
Wi	lireless	Two integrated wireless antennas
Eti	thernet port	Two RJ-45 ports included for maintenance and access to the internally mounted NX102 unit.
Signal Dig	igital I/O	Eight PNP (sourcing) inputs Eight PNP (sourcing) outputs
	nalog I/O	Four -10 to +10 VDC analog inputs
۸.	udio	
Signal Die Interfaces Ar	igital I/O nalog I/O	Eight PNP (sourcing) inputs Eight PNP (sourcing) outputs Four -10 to +10 VDC analog inputs Four -10 to +10 VDC analog outputs
Au	udio	Digital audio out

HD Series

	Item	Details
	Safety Scanning Lasers	Two Safety Scanning Lasers are included to provide a 360° detection area around the AMR. The scanning plane is positioned 175 mm above the floor. Lasers are rated as Class 1, eye-safe, PLd Safety per ISO 13849-1.
	E-STOP Buttons	Five E-STOP buttons are located on the AMR (sides and Operator Panel). Additional E-STOP buttons can be added to the payload structure.
	Low Lasers	Two Low Lasers are provided to detect objects near the floor.
Safety Features	Side Lasers (optional)	Two lasers, factory-mounted above safety scanning lasers, user-relocatable to the payload structure if needed.
2	Visual Indicators	Light discs are located on the sides of the AMR. Light strips are located on the front and back of the AMR. Additional indicators can be added.
	Audible Indicators	Two speakers are included. Additional buzzers can be added.
	Emergency Stop Interface	Dual channel emergency stop inputs and outputs.
	Safety Outputs	Dual channel safety outputs.
	Protective Stop Interface	Dual channel protective stop inputs.
	Display	7-inch diagonal LCD.
Operator Panel	Controls	 E-STOP button ON/OFF buttons Brake release button Pendant port Maintenance port Main disconnect switch

*1. Auxiliary power draw will impact these times

MobilePlanner Software

	Operating System	Windows 10 (32-bit/64-bit version)	
MobilePlanner, PC	CPU	1.5 GHz dual-core CPU recommended	
	Main Memory	1.5 GB min. (4 GB min. recommended)	
	Hard Disk	At least 200 MB of available space	
	Video Memory	256 MB min.	
	Display	XGA 1024 \times 768, 16 million colors minimum	
MobilePlanner, Tablet Edition	Operating	Android OS, Version 9 or newer, minimum 2 GB of RAM	
Tablet Edition	System	iOS, Version 10 or newer	
Supported Languages		English, German, Japanese, French, Italian, Korean, Spanish, Simplified Chinese and Traditional Chinese.	

EM2100 Appliance

Weight	9.1 kg
Mounting method	1U rack mount in a standard 19-inch equipment rack
Power Supply	100 to 240 VAC (typical 100 W)
Power Consumption	200 W max.
Operating Temperature	10 to 35°C
Storage Temperature	-25 to 60°C
Operating Humidity	8 to 90%, non-condensing
Storage Humidity	5 to 95%, non-condensing
Ingress Protection Class	IP20
Main Memory	32 GB DDR3
Storage	60 GB SSD
Archive Storage	4 TB HDD
Communication port	10/100/1000 Ethernet × 4, USB × 4, VGA
Status Display	Multi-segment LCD

Charging Station

Maximum Current	Input current: 25 A Output current: 120 A (nominal) *1
Input Voltage	3-phase 200 to 240 VAC, 50/60 Hz (Delta/Wye) 380 to 415 VAC, 50/60 Hz (Wye only)
Output voltage	40 to 57 VDC
Power Consumption	7.75 kW
Maximum Power Output	6.84 kW
Humidity	5 to 95%, non-condensing
Ambient Operating Temperature	5 to 40°C
Storage Temperature	-20 to 60°C
Ingress Protection Class	IP20 (IP10 for charging pads)
Weight	Power Supply Box: 108 kg Docking Target: 27.5 kg
Docking Target Mounting	To floor and/or wall

*1. Fused at 150 A

High Accuracy Positioning System

Ingress Protection	n	IP64		
Environment		-40 to 85°C		
Magnetic Tene	Width	25 mm		
Magnetic Tape	Orientation	South up		
	Width	25 mm		
Markers	Length	300 mm min. for 500 mm/s drive speed		
(Magnetic Tape)	Orientation	North up		
	Separation from tape	20 to 30 mm		
Protective covering tape (recommended)		Mighty Line Safety Floor Tape, Solid (102 mm width)		
Stop Position	Single AMR	± 8 mm position, $\pm 0.4^{\circ}$ rotation		
Repeatability	Fleet	± 10 mm position, $\pm 0.75^{\circ}$ rotation.		

Cell Alignment Positioning System (CAPS)

Stop Position Repeatability - Single AMR	± 8 mm position, $\pm 0.5^\circ$ rotation
Stop Position Repeatability - Fleet	± 16 mm position, $\pm 0.5^\circ$ rotation
Туре	Software license

Pendant

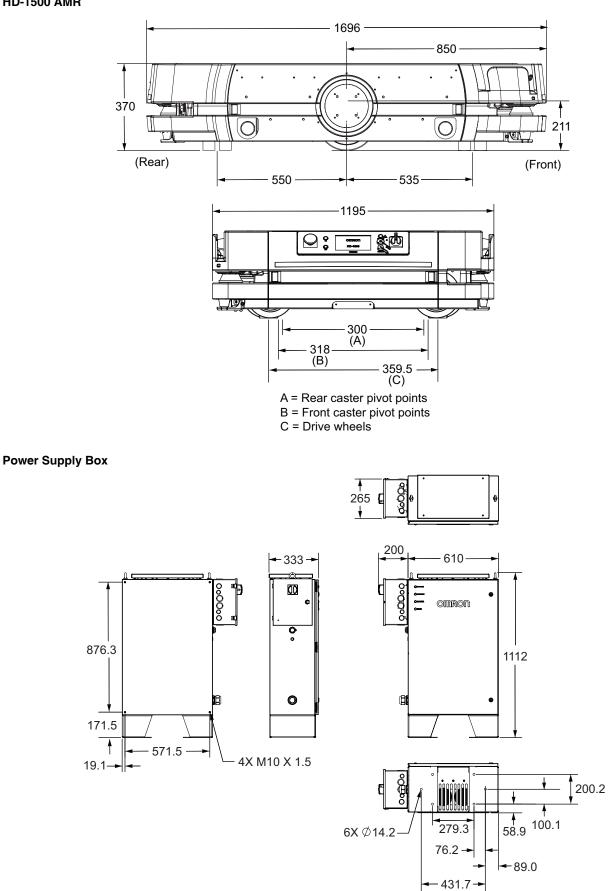
Ambient Operating Temperature	0 to 40°C
Storage Temperature	-20 to 65°C
Humidity	5 to 95%, non-condensing
Altitude	2000 m
Ingress Protection Class	IP30

Battery

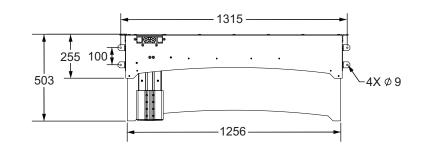
Ballory		
Voltage	48 to 56 VDC (52.8 nominal)	
Capacity	70 Ah nominal	
Recharge Time	40 min (from empty to full)	
Charge Cycles	9000 recharge cycles (battery cell nominal)	
Charging Method	Automatic or manual	
Ambient Operating Temperature	5 to 40°C	
Storage Temperature	-20 to 60°C (less than 2 weeks) -20 to 35°C (more than 2 weeks)	
Humidity	5 to 95%, non-condensing	
Altitude	4500 m, operating 15240 m, transporting	
Ingress Protection Class	IP20	
Weight	69.5 kg	

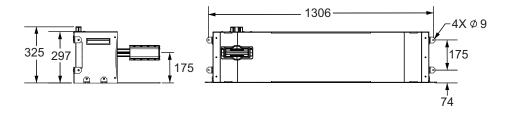
HD Series Dimensions

HD-1500 AMR

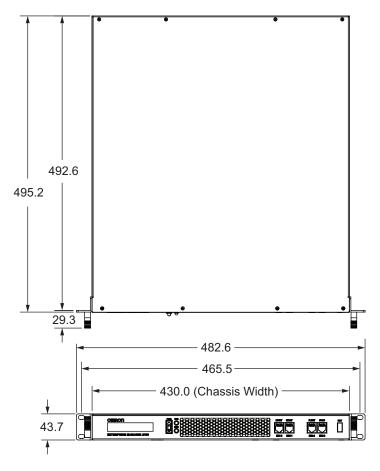


Docking Target





Fleet Manager EM2100 Appliance



HD Series

Related Manuals

Manual No.	Title
l614	Mobile Robot Software Suite User's Guide
l617	Advanced Robotics Command Language Reference Manual
l618	Advanced Robotics Command Language Enterprise Manager Integration Manual
1634	EM2100 Installation Manual
1635	Fleet Operations Workspace Core User's Manual
1636	Fleet Operations Workspace Core Migration Manual
1637	Fleet Operation Workspace Core Integration Toolkit User Manual
1649	Fleet Simulator User's Manual
1645	HD-1500 Platform User's Manual
1647	Mobile Robot HD Safety Manual

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Regional Headquarters OMRON EUROPE B.V. Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388 OMRON ASIA PACIFIC PTE. LTD. No. 438A Alexandra Road # 05-05/08 (Lobby 2), Alexandra Technopark, Singapore 119967 Tel: (65) 6835-3011/Fax: (65) 6835-2711	OMRON ELECTRONICS LLC 2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787 OMRON ROBOTICS AND SAFETY TECHNOLOGIES, INC. 4225 Hacienda Drive, Pleasanton, CA 94588 U.S.A. Tel: (1) 925-245-3400/Fax: (1) 925-960-0590 OMRON (CHINA) CO., L HTD. Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200	© OMRON Corporation 2020-2022 All Rights Reserved. In the interest of product improvement, specifications are subject to change without notice. CSM_2_1 Cat. No. 1855-E-04 0122(0720)